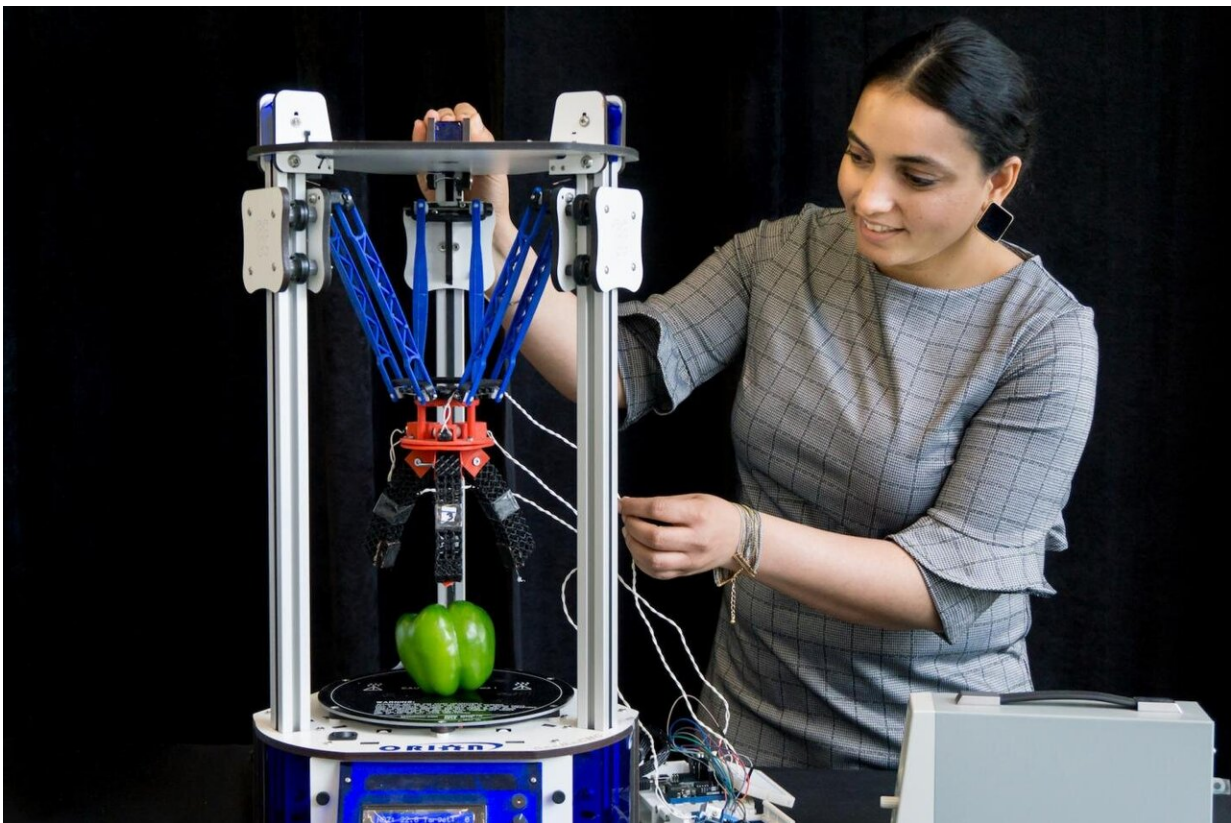


# Innovative robot fingers hold promise for assistive living, prosthetics

June 11 2019, by Ariane Madden

---



SFU PhD graduate Manpreet Kaur works in the field of soft robotics and demonstrates 3-D printed humanoid robot 'fingers.' Credit: SFU

There's nothing quite like the comforting squeeze of your partner's hand. But a robot's hand? That's perhaps a bit different.

Now, a Simon Fraser University mechatronics graduand has designed 3-D-printed humanoid robot "fingers" that mimic the strength and tenderness of a human hand. For people with mobility challenges or limb differences, robots equipped with these flexible fingers could prove important companions or tools for independent living.

"In this field, called [soft robotics](#), we take inspiration from nature to create [materials](#) for robots that can safely interact with humans," says Manpreet Kaur, who developed the 3-D-printed humanoid fingers as part of her recent Ph.D. thesis, supervised by mechatronic systems engineering professor Woo Soo Kim. Kaur graduates this week, after successfully defending her thesis in April.

Today's commercially available robots are often made with hard materials that, when used improperly, could scratch or impale their human operators, or are simply uncomfortable to interact with. Conversely, many of the materials that make up so-called [soft robots](#)—such as inflatable or jelly-like robots—may be too soft to carry loads and can be easily punctured with regular use and human interaction.

"We need something that takes advantage of the flexibility and gentleness of those soft materials but is also strong and durable enough to complete different tasks," Kaur explains.

Robotics manufacturers and researchers have sought to create robotic personal assistants and bionic limbs or prosthetics that combine the durability of common robots with the gentleness of a soft [robot](#).

To address the challenge, Kaur designed a new robotic body that might just have the right touch.

In SFU's Additive Manufacturing Laboratory, Kaur developed lightweight, 3-D-printed polymers structured with a unique truss design

that can be "tuned" to different rigidities—from soft and rubbery to hard and metallic.

"The beauty of using 3-D printing is that it gives us the ability to manufacture the fingers very efficiently," says Kim, who leads the development of sustainable 3-D-printing materials and whose lab will further develop the technology now that Kaur is graduating.

"The process is easily scalable. And, 3-D printing can use less-wasteful and more sustainable materials in the manufacturing itself."

While the 3-D printer makes the fingers, Kaur embeds sensors (also 3-D-printed) that detect pressure and strain, mimicking a human's ability to sense the squeeze of a hand. The material is flexible and moves like a human finger but also has shock- and vibration-absorption properties that are suitable for the electrical components it will contain.

Kaur and Kim then tested the robotic finger technology by creating a robotic gripper capable of adeptly handling soft objects such as bell peppers, tomatoes—even eggs—without breaking or puncturing the objects. The technology could have applications in new kinds of [prosthetic](#) limbs and humanoid robots that are both durable enough for everyday use, and soft enough to complete delicate tasks.

The research is expected to be published this summer while the team awaits news on a patent for which they've applied. Kaur is also collaborating with fellow researchers to create a robotic prosthetic hand from her innovation.

"To see my results getting used for an application like this, it's very meaningful to me," says Kaur. "This research is very exciting and I look forward to seeing how it can make robots safe and accessible for others."

Provided by Simon Fraser University

Citation: Innovative robot fingers hold promise for assistive living, prosthetics (2019, June 11) retrieved 30 January 2023 from <https://techxplore.com/news/2019-06-robot-fingers-prosthetics.html>

This document is subject to copyright. Apart from any fair dealing for the purpose of private study or research, no part may be reproduced without the written permission. The content is provided for information purposes only.