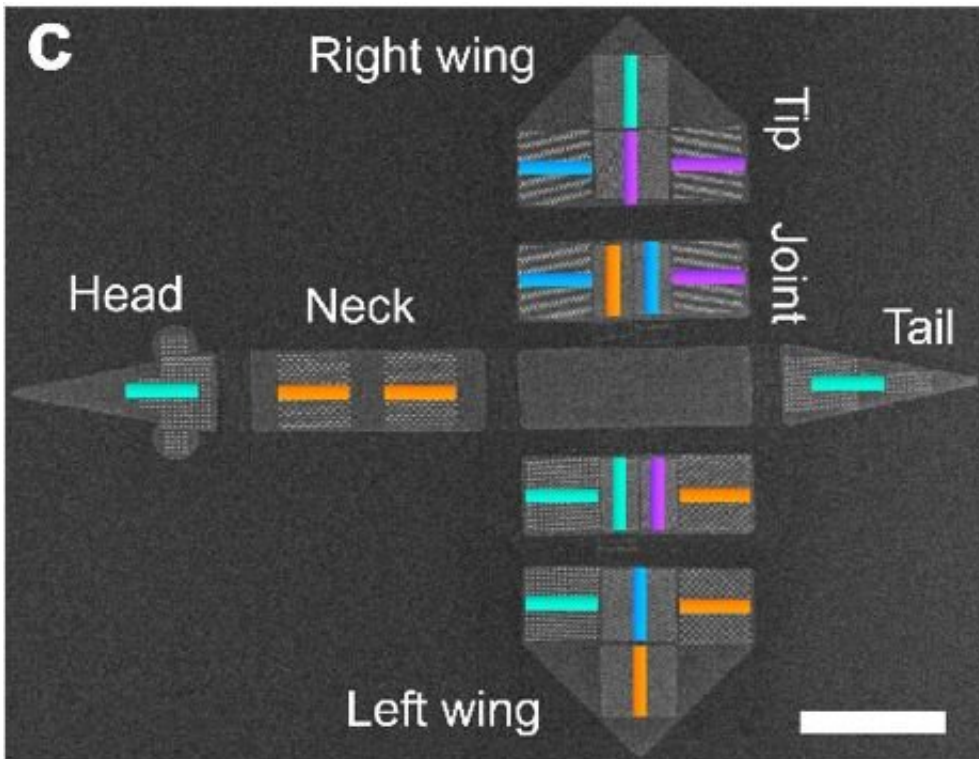


# On the way to intelligent microrobots

November 6 2019, by Sebastian Jutzi



The scanning electron microscope image shows the bird-like construct with arrangements of nanoscale magnets. The magnets can be magnetised in different orientations parallel to the colour bars. By programming their magnetisation, the researchers can make bird carry out different movements in a magnetic field. Credit: Paul Scherrer Institute/Swiss Federal Institute of Technology, Zurich

Researchers at the Paul Scherrer Institute PSI and ETH Zurich have developed a micromachine that can perform different actions. First nanomagnets in the components of the microrobots are magnetically

programmed and then the various movements are controlled by magnetic fields. Such machines, which are only a few tens of micrometers across, could be used, for example, in the human body to perform small operations. The researchers have now published their results in the scientific journal *Nature*.

The robot, which measures only a few micrometers across, is reminiscent of a paper bird made with origami—the Japanese art of paper folding. But, unlike a paper structure, the robot moves as if by magic without a visible force. It flaps its wings or bends its neck and retracts its head. These actions are all made possible by magnetism.

Researchers at the Paul Scherrer Institute PSI and ETH Zurich have assembled the micromachine from materials that contain small nanomagnets. These nanomagnets can be programmed to assume a particular magnetic orientation. When the programmed nanomagnets are then exposed to a magnetic field, specific forces act on them. If these magnets are located in flexible components, the forces acting on them cause the components to move.

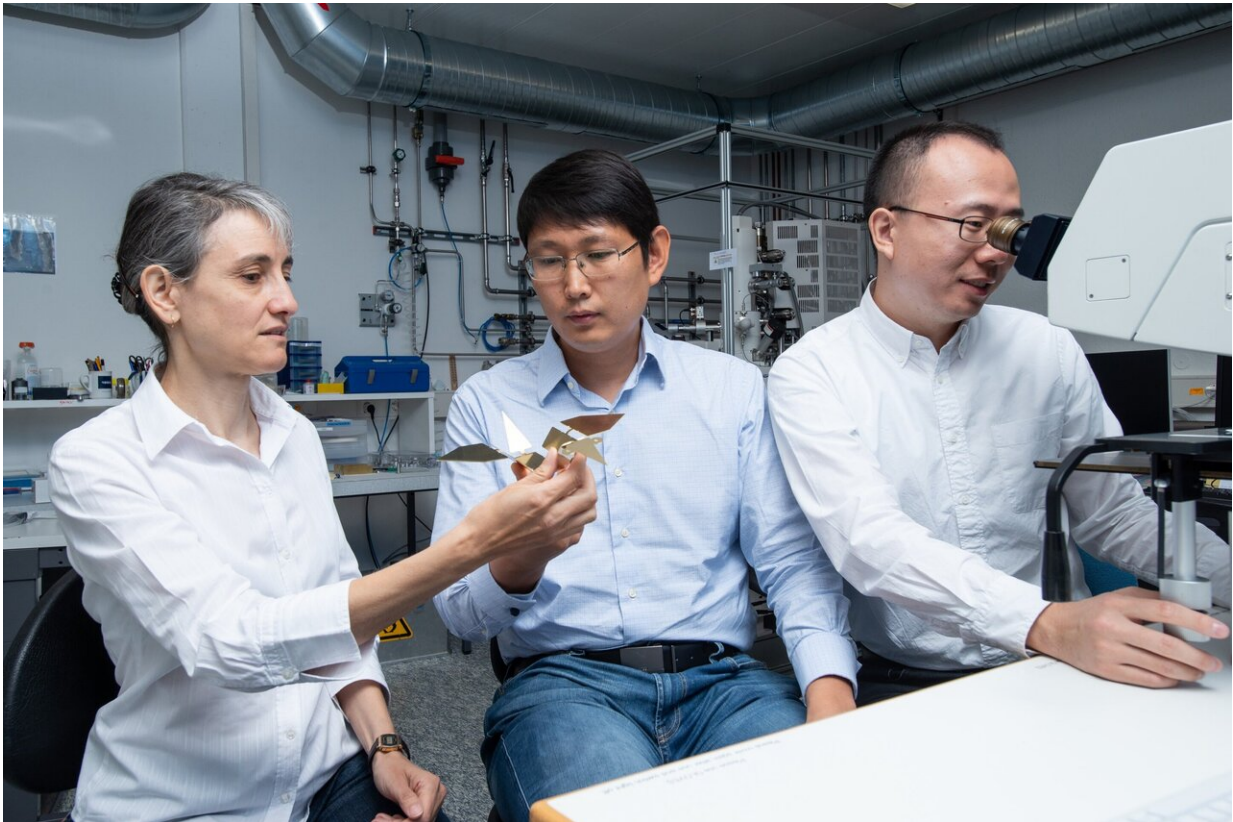
## **Programming the nanomagnets**

The nanomagnets can be programmed again and again. This reprogramming results in different forces, and new movements result.

For the construction of the microrobot, the researchers fabricated arrays of cobalt magnets on thin sheets of silicon nitride. The bird constructed from this material could then perform various movements, such as flapping, hovering, turning or side-slipping.

"The movements performed by the microrobot take place within milliseconds," says Laura Heyderman, head of the Laboratory for Multiscale Materials Experiments at PSI and professor for Mesoscopic

Systems at the Department of Materials, ETH Zurich. "But programming of the nanomagnets only takes a few nanoseconds. This makes it possible to program the different movements one after the other. This means that the tiny microbird can first flap its wings, then slip to the side and afterwards flap again. "If needed, the bird could also hover in between," says Heyderman.



Laura Heyderman (left) and Tian-Yun Huang (center) look at a model of the origami bird, while Jizhai Cui observes the real microrobot under a microscope. What he can see is shown in the video made by the researchers. Credit: Paul Scherrer Institute/Mahir Dzambegovic

## Intelligent microrobots

This novel concept is an important step towards micro- and nanorobots that not only store information to give a particular action, but also can be reprogrammed to carry out different tasks. "It is conceivable that, in the future, an autonomous micromachine will navigate through human blood vessels and perform biomedical tasks such as killing cancer cells," explains Bradley Nelson, head of Department of Mechanical and Process Engineering at ETH Zurich. "Other application areas are also conceivable, for example flexible microelectronics or microlenses that change their [optical properties](#)," says Tianyun Huang, a researcher at the Institute of Robotics and Intelligent Systems at ETH Zurich.

In addition, applications are possible in which the characteristics of surfaces change. "For example, they could be used to create surfaces that can either be wetted by water or repel water," says Jizhai Cui, an engineer and researcher in the Mesoscopic Systems Lab.

**More information:** Nanomagnetic Encoding of Shape-morphing Micromachines Jizhai Cui, Tian-Yun Huang, Zhaochu Luo, Paolo Testa, Hongri Gu, Xiang-Zhong Chen, Bradley J. Nelson, Laura J. Heyderman *Nature*, 06.11.2019 [DOI: 10.1038/s41586-019-1713-2](https://doi.org/10.1038/s41586-019-1713-2) , [nature.com/articles/s41586-019-1713-2](https://www.nature.com/articles/s41586-019-1713-2)

Provided by Paul Scherrer Institute

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