

Energy-generating synthetic skin for affordable prosthetic limbs and touch-sensitive robots

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A new type of energy-generating synthetic skin could create more affordable prosthetic limbs and robots capable of mimicking the sense

of touch, scientists say.

In an early-view paper published in the journal *IEEE Transactions on Robotics*, researchers from the University of Glasgow describe how a [robotic hand](#) wrapped in their flexible solar [skin](#) is capable of interacting with objects without using dedicated and expensive [touch sensors](#).

Instead, the skin puts the array of miniaturized [solar cells](#) integrated on its soft polymer surface to a clever dual use. The cells generate enough energy to power the micro-actuators which control the hand's movements, but they also provide the hand with its unique sense of 'touch' by measuring the variations in the solar cells' output.

As objects get closer to the surface of a cell, they reduce the amount of light which reaches it. The amount of power the cell generates drops as the light gets dimmer, eventually reaching zero when an object touches and covers it. By making clever interpretations of the levels of power produced in each cell, the skin is capable of detecting the shape of an incoming object.

A second set of simple LEDs, integrated between the solar cells in the skin, transmit infra-red light towards objects. By measuring the time the light takes to reflect from the object, the skin can sense the distance between the object and the hand.

Combining the information collected from the solar [cells](#) and LEDs allows the skin's processor to deduce an object's proximity, location, and edges, replicating many of the parameters measured by more traditional touch sensors. Together, the data allows the hand to grasp objects like rubber balls placed in front of it.

It's the latest development in electronic skin from the University of Glasgow's Bendable Electronics and Sensing Technologies (BEST)

Group, led by Professor Ravinder Dahiya.

Professor Dahiya, of the University's James Watt School of Engineering, said: "Touch-sensitive electronic skin has found numerous experimental applications in prosthetics and robotics in recent years, but our project is the first energy-generating e-skin capable of offering touch feedback without using dedicated touch sensors.

"That lack of sensors means the skin requires no conventional power source to work, unlike other equivalent devices which include touch sensors. In fact, the skin itself is the source of energy, capable of powering the hand and devices attached to it. The generated power can be stored in devices such as flexible supercapacitors we've developed to work alongside the skin, so it doesn't have to be constantly exposed to the sun in order to work.

"It's one step closer to a completely self-powered prosthetic wrapped in flexible skin made from relatively inexpensive components. The sensing capabilities built into the skin could even lead to skin that can 'see' – further refinements could help the skin identify approaching objects even before they make contact."

"We've also experimented with adding the [hand](#) to the end of a robot arm, similar to the ones found in places like car manufacturing facilities. The skin's sensors are capable of stopping the arm's motion when it senses an unexpected [object](#), which we believe could help prevent future industrial accidents."

The team's paper, titled "Energy Generating Electronic Skin With Intrinsic Tactile Sensing Without Touch Sensors," is published in early access in *IEEE Transactions on Robotics*.

More information: Pablo Escobedo et al. Energy Generating

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