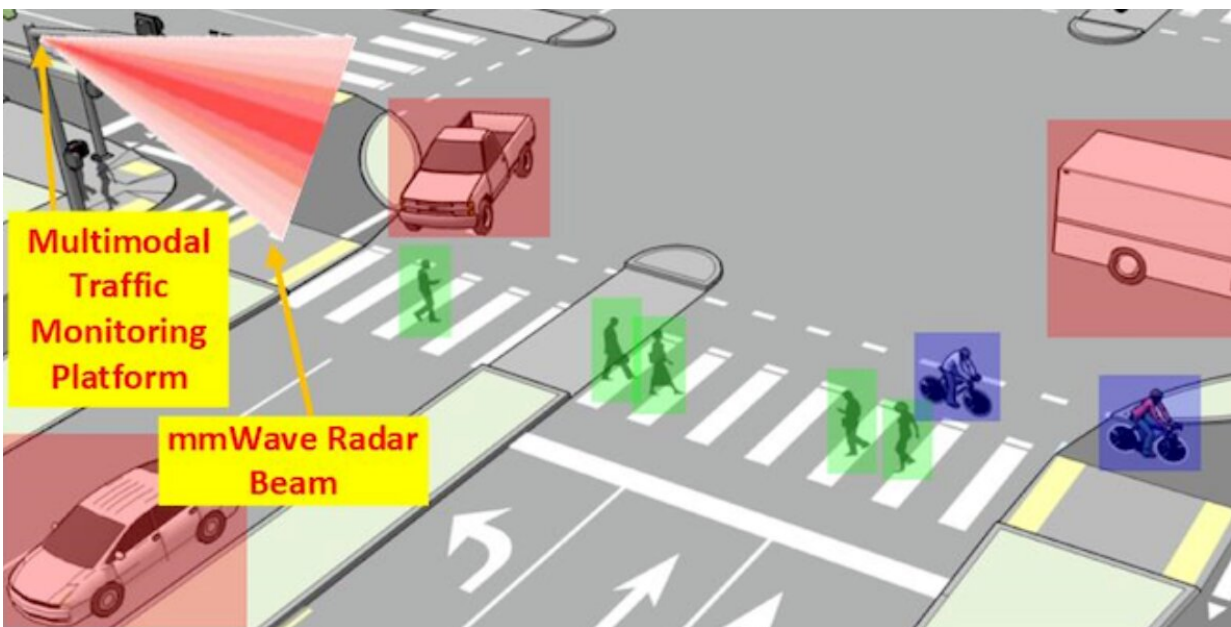


New radar sensor technology for intelligent multimodal traffic monitoring at intersections

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Credit: Portland State University

Intelligent Transportation Systems (ITS) need traffic data to run smoothly. At intersections, where there is the greatest potential for conflicts between road users, being able to reliably and intelligently monitor the different modes of traffic is crucial.

The Federal Highway Administration (FHWA) estimates that more than

50 percent of the combined total of fatal and injury crashes occur at or near intersections. For pedestrians the intersection is a particularly dangerous place: the City of Portland, Oregon identified that two-thirds of all crashes involving a pedestrian happen at intersections. And when darkness comes earlier in fall and winter, crashes increase dramatically. So knowing what's going on in low-visibility conditions is essential for mobility and safety of all road users.

Some agencies use cameras to monitor traffic modes, but cameras are limited in rainy, dark or foggy conditions. Some cities use [radar](#) instead of cameras, which works better in low-visibility but typically can't provide as rich a picture of what's going on. Conventional radar gives movement and position data for all approaching entities, but it's very hard to tell the difference between modes with any reliability.

In the latest report funded by the National Institute for Transportation and Communities (NITC), *Development of Intelligent Multimodal Traffic Monitoring using Radar Sensor at Intersections*, researchers Siyang Cao, Yao-jan Wu, Feng Jin and Xiaofeng Li of the University of Arizona have tackled the issue by developing a high-resolution radar sensor that can reliably distinguish between cars and pedestrians. This sensor also supplies the counts, speed, and direction of each moving target, no matter what the lighting and weather are like. In the future, they plan to further refine their model to interpret more complex data and be able to identify additional modes.

Why use mmWave radar?

The [prototype device](#) used a high-resolution millimeter-wave (mmWave) radar sensor that outperforms cameras in low-visibility conditions and beats conventional radar by providing a richer picture.

"The mmWave radar is also different from other sensors in that it can

provide relatively stable radial velocity, which is very helpful for us to identify the speed of vehicles," Cao said.

This gives the system an advantage over light-based sensors like LiDAR. LiDAR systems are able to "see" in great detail, making it easy to determine what an object is; but they have difficulty with movement and speed. MmWave radar can resolve the speed of a moving target much more reliably than LiDAR.

"The key problem in multimodal traffic monitoring is finding the speed and volume of each mode. A sensor must be able to detect, track, classify, and measure the speed of an object, while also being low-cost and low power consumption. With real-time traffic statistics we hope to improve traffic efficiency and also reduce the incidence of crashes," Cao said.

The mmWave radar sensor also works on a lower frequency band than LiDAR, making it more stable under different weather conditions (rain, snow, fog, smoke, etc.). In multimodal traffic monitoring, sensors need to be employed outdoors, so mmWave radar is an optimal choice.

Testing the sensor at an intersection

The research team developed a multivariate Gaussian mixture model (GMM) to interpret the information from the mmWave radar sensor. First, the sensor obtains a rich radar point cloud representation. Then the model segments the point clouds into three kinds of objects: pedestrian, sedan, and "clutter." Clutter just refers to non-moving surfaces like buildings, trees or other objects. Once this is done, the data stream is transmitted wirelessly to a laptop and displayed as a visual image. In the lab, Cao and his students calibrated the device so that its output would match what a camera sees.

The prototype built by the UA research team is low-cost, low-weight, and of a compact size that's easy to install. The researchers installed their sensor at an intersection in Tucson and set up a laptop in a nearby parking lot to test it. With the GM model they developed, it yielded promising results at both detecting and correctly identifying objects.

Signalized intersections like the test site are critical spots for collecting such mixed-[traffic data](#), because the most conflicts and crash occurrences tend to involve multiple transportation modes.

Expanding technology for multimodal traffic

"We realize that sensor technology is moving to a stage that's going to have a lot of new applications. On one hand, the cost of [sensors](#) is dropping and their performance is improving significantly. Meanwhile the surrounding technology—for example battery technology, communications, and computation enabled by artificial intelligence—is also improving. For multimodal traffic monitoring, a sensor can collect information that can be shared with drivers via a next-generation communication network to improve mobility and safety at intersections," Cao said.

In the future, the researchers hope to further refine the model to be able to identify additional modes such as motorcycles, bikes, trucks and busses. Once refined, this sensor could play a key role in facilitating a reliable and accurate city-wide traffic network. The project's GitHub repository offers more information, including data, video and images from the test deployment.

In addition, the outcomes of this project (the GMM and the prototype) offer useful insights for people developing other advanced technologies to create equitable, healthy, and sustainable smart cities. Through leading in the development and deployment of innovative practices and

technologies, this research can help improve the safety and performance of the nation's transportation system.

More information: Report: nrtc.trec.pdx.edu/research/project/1296

GitHub: github.com/radar-lab/traffic_monitoring

Provided by Portland State University

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