

Vehicular mobility patterns and their applications to internet-of-vehicles: A comprehensive survey

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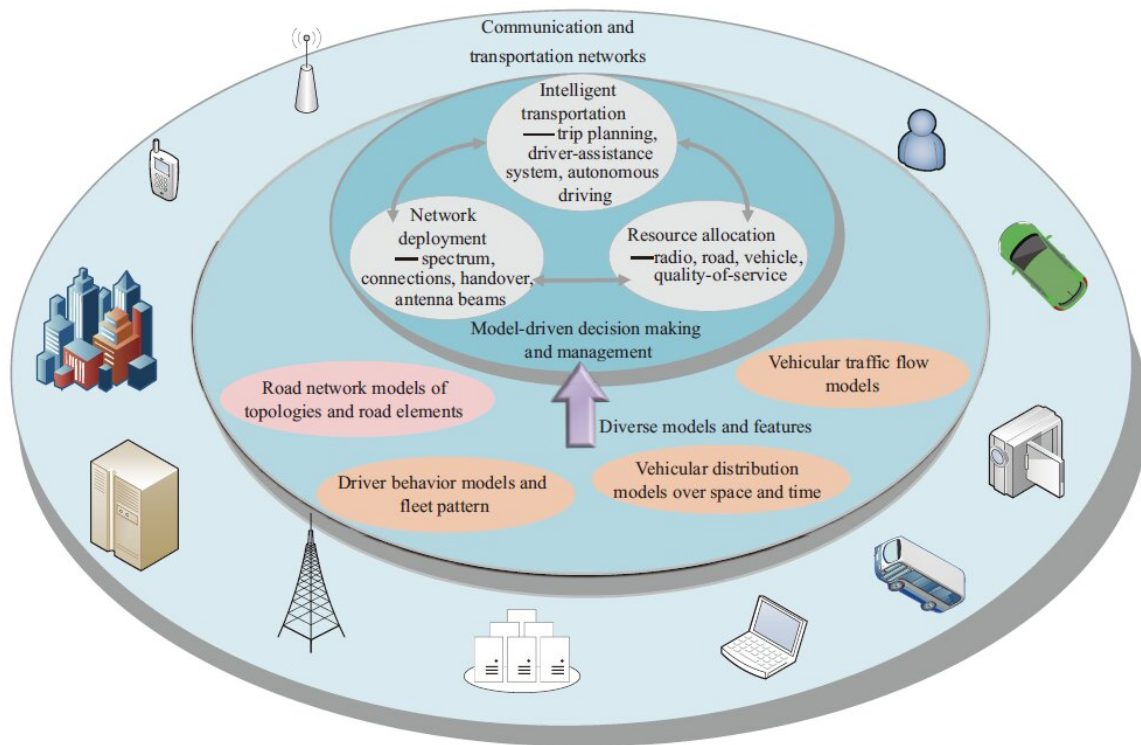


Figure. 1 Framework for model-driven applications in smart city. Credit: Science China Press

Increasingly equipped with wireless interfaces, vehicles including driver-less vehicles make up a significant part of ubiquitous connection. As a

consequence, not only do wireless networks grow quickly in terms of network scale, coverage and density, but become increasingly abundant of dynamics and variations such as fast-changing network topologies, channel states, and service demands.

Driven by [big data](#), it is anticipated that learning techniques such as machine learning or [deep learning](#) will address many challenging communication and networking problems which have not been adequately addressed using optimization techniques and analyses.

The Internet-of Vehicles (IoV) is characterized by large-scale networks and continuous changes in the networks, and strong coupling in both the time and space domains. An application of learning techniques to the IoV is not trivial because of the network scale, continuous network changes, and strong network coupling.

Feature extraction is an effective way to reduce this input, facilitate the data-driven learning process, and improve efficiency. The vehicular mobility models are generated to share the features, rather than huge amounts of raw data, between the cities. This is expected to significantly reduce the bandwidth requirements, improve the generalization of learning results, and protect privacy.

This [survey](#) reviews the status quo of vehicular mobility models, with a particular emphasis on the recent results in the past decade. Existing vehicular mobility models are categorized into vehicular distribution, [vehicular traffic](#), and driving behavior models.

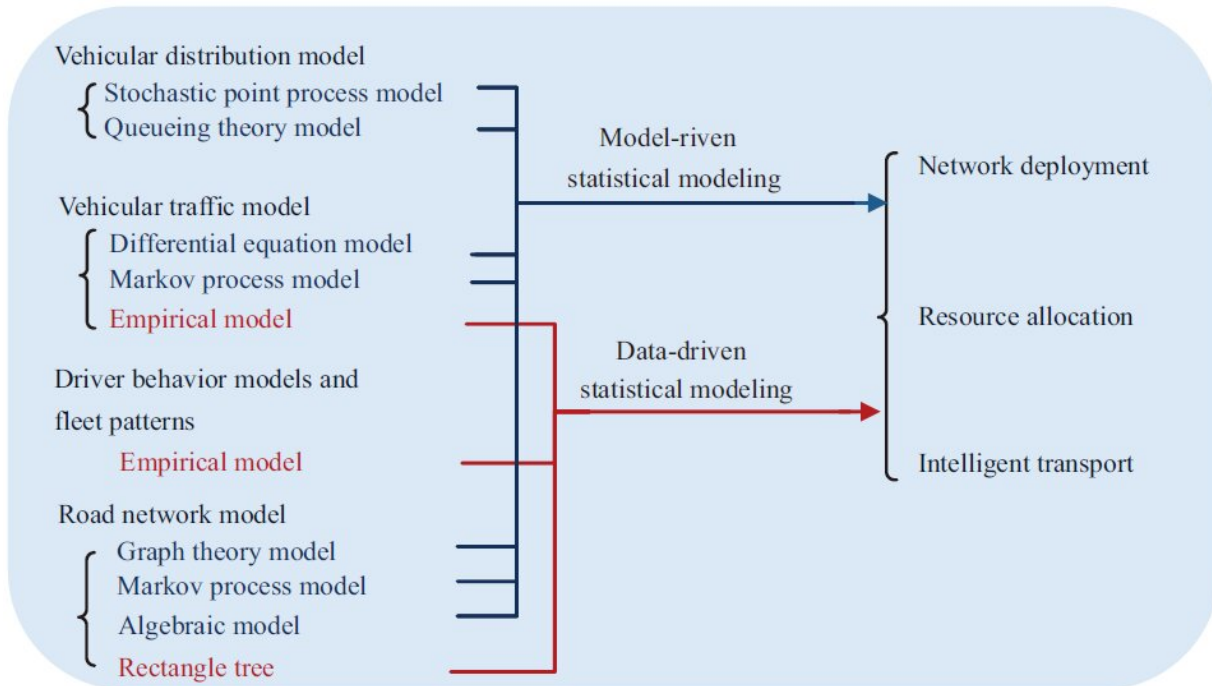


Figure 2. Classification of models based on application scenes. The red font models are data-driven, the blue font models are model-driven, and the four types of models support three applications: network deployment, resource allocation, and intelligent transportation. Credit: Science China Press

Such categorization has a particular emphasis on the random patterns of vehicles in space, traffic flow models aligned to road maps, and individuals' driving behaviors (e.g., lane-changing and car-following). The different categories of the models are applied to various application scenarios, including underlying network connectivity analysis, off-line network optimization, online network functionality, and [real-time](#) autonomous driving.

We summarize the related application examples to cover a wide range of application scenarios in Intelligent Transport System (ITS). We assess the practicality of the models in the actual context of the ITS and discuss

the potential performance of existing models, according to the characteristics of different application scenarios. Finally, several important research opportunities arise and deserve continuing research effort.

More information: Qimei Cui et al, Vehicular mobility patterns and their applications to Internet-of-Vehicles: a comprehensive survey, *Science China Information Sciences* (2022). [DOI: 10.1007/s11432-021-3487-x](https://doi.org/10.1007/s11432-021-3487-x)

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