

Self-learning bionic hand could spark 'new generation' of prosthetic limbs

3 July 2018, by Caroline Brogan



3-D rendered image of the new prosthesis rotating to throw a ball. Credit: Imperial College London

The new prosthetic hand interprets muscular signals from brain activity with machine learning to make movements more natural.

Scientists at Imperial College London and the University of Göttingen have used machine learning to improve the performance of prosthetic hands.

After testing their prototype on five amputees, they found that new machine learning-based control was far better at providing natural, fluid movements than the currently available technology.

The researchers said the findings, which are published in *Science Robotics*, could spark a "new generation of [prosthetic limbs](#)."

Professor Dario Farina, senior author of the paper from Imperial's Department of Bioengineering, said: "When designing bionic limbs, our main goal is to let [patients](#) control them as naturally as though they were their biological limbs. This new technology takes us a step closer to achieving this."

Machine learning

Current technology works by directly controlling the prosthetic motors with a few muscular signals.

The new bionic [hand](#), developed in collaboration with Imperial and the University of Göttingen, uses a human-machine interface that interprets the patient's intentions and sends commands to the artificial [limb](#).

It contains eight electrodes that pick up weak electrical signals from the patient's stump, before amplifying them and sending them to a mini-computer, also located in the prosthetic.

The mini-computer then runs the machine learning algorithm to interpret the signals, before commanding the hand's motors to move in the way the patient wants.

Patients found they were able to easily rotate the wrist and open the hand either simultaneously or separately. They also found the movements far more natural than the conventional [bionic limbs](#) they were used to.

In addition to types of function, patients could also control the speed of individual [movement](#) independently of other movements. For example, patients could turn the hand slowly but open it quickly at the same time. The researchers say this is an essential component for movements that feel natural.

Prior to use, the patient and bionic hand underwent training so the machine learning algorithm could

'learn' how to interpret their unique electronic signals. Professor Farina hopes to eliminate the need for this in future prototypes, without sacrificing personalisation to specific patients.

Professor Farina said: "The new bionic hand is not only more natural but it is also superior in terms of functionality in daily tasks than what's currently available to patients.

"Following this clinical study, we hope to have this available on the market for patients within three years."

The researchers are currently working to gain greater control over the hand, including the ability to move individual fingers, and eliminate the need for electrodes by transferring signals wirelessly within the patient's body.

More information: Janne M. Hahne et al. Simultaneous control of multiple functions of bionic hand prostheses: Performance and robustness in end users, *Science Robotics* (2018). [DOI: 10.1126/scirobotics.aat3630](https://doi.org/10.1126/scirobotics.aat3630)

Provided by Imperial College London

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