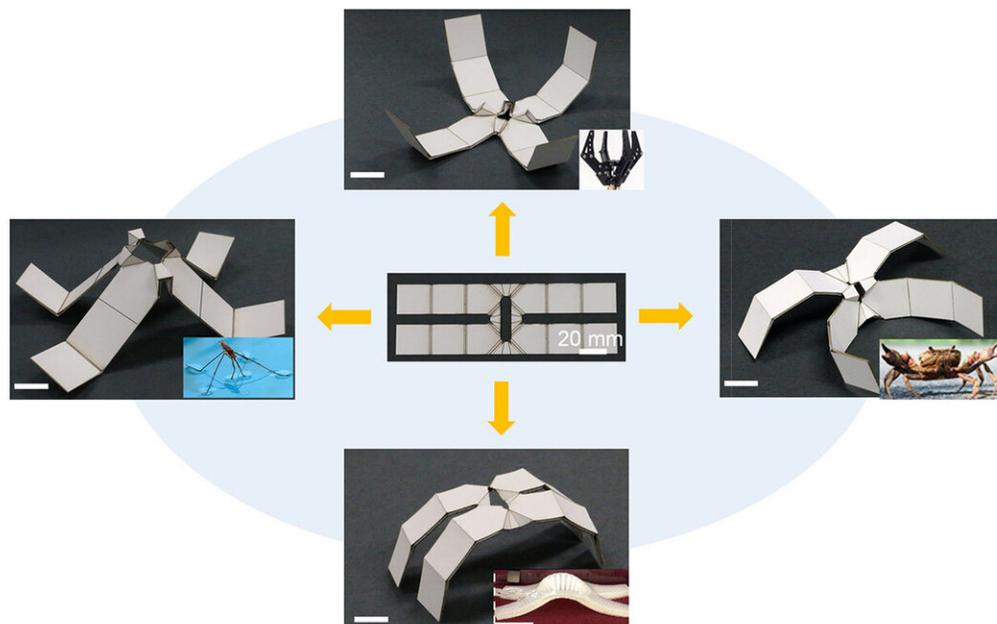


Researchers make robots from self-folding kirigami materials

December 16 2019



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Researchers have demonstrated how kirigami-inspired techniques allow them to design thin sheets of material that automatically reconfigure into new two-dimensional (2-D) shapes and three-dimensional (3-D) structures in response to environmental stimuli. The researchers created a variety of robotic devices as a proof of concept for the approach.

"This is the first case that we know of in which 2-D [kirigami](#) patterns autonomously reshape themselves into distinct 3-D structures without mechanical input," says Jie Yin, an assistant professor of mechanical and [aerospace engineering](#) at North Carolina State University and corresponding author of a paper on the work. "Instead, we apply energy in the form of heat, and the material rearranges itself."

Kirigami is an art form in which a single piece of paper is cut and folded to create new shapes and structures.

The new "active kirigami" concept relies on a three-layered material, consisting of two outer layers that are not responsive to heat, and a [polymer layer](#) in the middle that contracts in response to heat. The shape and [structure](#) of the material are controlled in two ways. Through-cuts, which penetrate all three layers, control the material's range of motion. Etchings, which penetrate the outer layers and expose the heat-responsive polymer, control the angle and direction at which the material folds, as well as how far it folds. As the material folds, it opens the through-cuts, shifting the shape of the sheets into 2-D or 3-D designs.

Video illustrating how active kirigami works can be seen below:

"We can make a 2-D template with the same pattern of through-cuts and use it to create many different 3-D structures by making slight changes in the etching," Yin says. "This effectively makes the active kirigami sheets programmable."

As part of their proof of concept, researchers used their kirigami approach to create a suite of thermoresponsive kirigami machines, including simple gripping devices and self-folding boxes. The researchers also created a soft robot with a kirigami body and pneumatic legs. By switching the orientation of the body, the researchers could rapidly reposition the legs, changing the robot's direction of movement. Video of the proof-of-concept machines:

"We used a temperature-responsive polymer for this work, but there's no reason to think that other stimuli-responsive polymer materials—like photoactive liquid crystals—wouldn't work as well," Yin says. "We're excited to explore the potential range of applications for these programmable, active kirigami materials."

The paper, "Programmable active kirigami metasheets with more freedom of actuation," will be published in the *Proceedings of the National Academy of Sciences*.

More information: Yichao Tang et al., "Programmable active kirigami metasheets with more freedom of actuation," *PNAS* (2019). www.pnas.org/cgi/doi/10.1073/pnas.1906435116

Provided by North Carolina State University

Citation: Researchers make robots from self-folding kirigami materials (2019, December 16) retrieved 20 September 2024 from <https://techxplore.com/news/2019-12-robots-self-folding-kirigami-materials.html>

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