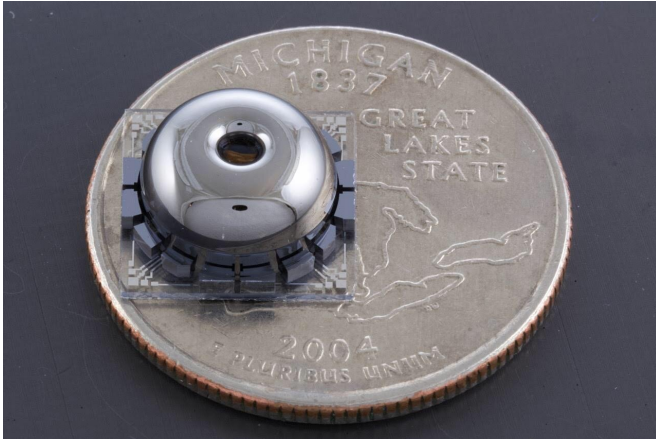


# Small, precise and affordable gyroscope for navigating without GPS

23 March 2020, by Kate McAlpine



The new resonator and electrodes, on a quarter for scale. The resonator is almost perfectly symmetrical, made of nearly-pure glass. This enables it to vibrate for long periods, similar to the ringing of a wine glass. Credit: Najafi Group, University of Michigan

A small, inexpensive and highly accurate gyroscope, developed at the University of Michigan, could help drones and autonomous cars stay on track without a GPS signal.

"Our gyroscope is 10,000 times more accurate but only 10 times more expensive than gyroscopes used in your typical cell phones. This gyroscope is 1,000 times less expensive than much larger gyroscopes with similar performance," said Khalil Najafi, the Schlumberger Professor of Engineering at U-M and a professor of electrical engineering and computer science.

Most smartphones contain gyroscopes to detect the orientation of the screen and help figure out which way we're facing, but their accuracy is poor. They're the reason why phones often incorrectly indicate which direction a user is facing during [navigation](#).

It doesn't matter much to a human on the street or behind the wheel, but a driverless car could get lost quickly with a loss of GPS signal. Inside their backup navigation systems, autonomous vehicles currently use high-performance gyroscopes that are larger and much more expensive.

"High-performance gyroscopes are a bottleneck, and they have been for a long time. This gyroscope can remove this bottleneck by enabling the use of high-precision and low-cost inertial navigation in most autonomous vehicles," said Jae Yoong Cho, an assistant research scientist in electrical engineering and computer science.

Better backup navigation equipment could also help soldiers find their way in areas where GPS signals have been jammed. Or in a more mundane scenario, accurate indoor navigation could speed up warehouse robots.

The device that enables navigation without a consistent orienting signal is called an inertial measurement unit. It is made up of three accelerometers and three [gyroscopes](#), one for each axis in space. But getting a good read on which way you're going with existing IMUs is so pricey that it has been out of range, even for equipment as expensive as autonomous vehicles.

The key to making this affordable, small gyroscope is a nearly symmetrical mechanical resonator. It looks like a Bundt pan crossed with a wine [glass](#), made one centimeter wide. As with [wine glasses](#), the duration of the ringing tone produced when the glass is struck depends on the quality of the glass—but instead of being an aesthetic feature, the ring is crucial to the gyroscope's function. The complete device uses electrodes placed around the glass resonator to push and pull on the glass, making it ring and keeping it going.

"Basically, the glass resonator vibrates in a certain pattern. If you suddenly rotate it, the vibrating

pattern wants to stay in its original orientation. So, by monitoring the vibration pattern it is possible to directly measure [rotation rate](#) and angle," said Sajal Singh, a doctoral student in electrical and computer engineering who helped develop the manufacturing process.

The way that the vibrating motion moves through the glass reveals when, how fast and by how much the gyroscope spins in space.

To make their resonators as perfect as possible, Najafi's team starts with a nearly perfect sheet of pure glass, known as fused-silica, about a quarter of a millimeter thick. They use a blowtorch to heat the glass and then mold it into a Bundt-like shape—known as a "birdbath" resonator since it also resembles an upside-down birdbath.

Then, they add a metallic coating to the shell and place electrodes around it that initiate and measure vibrations in the glass. The whole thing is encased in a vacuum package, about the footprint of a postage stamp and half a centimeter tall, which prevents air from quickly damping out the vibrations.

The paper, "0.00016 deg/°hr angle random walk (ARW) and 0.0014 deg/hr bias instability (BI) from a 5.2M-Q and 1-cm precision shell integrating (PSI) gyroscope," is scheduled to be presented at the (now virtual) 7th IEEE international Symposium on Inertial Sensors & Systems, on Wednesday, March 25.

**More information:**

[epapers.org/inertial2020/ESR/paper/0jqat2&paper\\_id=1088](https://epapers.org/inertial2020/ESR/paper/0jqat2&paper_id=1088)

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