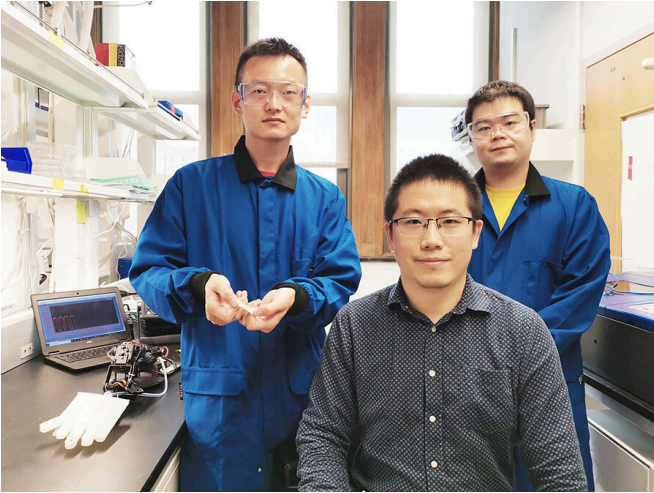


# Stretchable pressure sensor could lead to better robotics, prosthetics

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Stretchable pressure sensors like the one developed by Asst. Prof. Sihong Wang (center) and PhD students Qi Su (left) and Yang Li (right) could enable long-sought after applications in soft robotics. Credit: University of Chicago

In the future, soft robotic hands with advanced sensors could help diagnose and care for patients or act as more lifelike prostheses.

But one roadblock to encoding soft robotic hands with human-like sensing capabilities and dexterity has been the stretchability of [pressure](#) sensors. Although pressure sensors—needed for a robotic hand to grasp and pick up an object, or even take a pulse from a wrist—have been able to bend or stretch, their performance has been significantly affected by such movement.

Researchers at the Pritzker School of Molecular Engineering (PME) at the University of Chicago have found a way to address this issue and have designed a new pressure sensor that can be stretched up to 50 percent while maintaining almost the same sensing performance. It is also sensitive enough to sense the pressure of a small

piece of paper, and it can respond to pressures almost instantaneously.

The researchers attached the sensor to a soft robotic hand, which was then able to use it to take the pulse waveforms—the dynamic pressure pattern within each beating of pulse—from a human wrist. The results were published November 24 in *Science Advances*, and the researchers have filed a patent for the technology.

"This the first pressure sensor that can stretch and still maintain its [high sensitivity](#) and quick response rate," said Asst. Prof. Sihong Wang, who led the research. "It could potentially be important technology, both in the research community and in the healthcare industry."

## A special double-layer design

Creating [pressure sensors](#) that can work on soft robotics has been difficult, since the stretched skin of [soft robotics](#) could introduce lateral strain to the pressure sensor. This introduces another mechanical signal into the system, making it difficult to decouple pressure and strain into separate measurements.

Wang's graduate student, Qi Su, led the development of a sensor that works through a new electrical double layer design. The outside layers are made up of stretchy, conductive nanoparticle paste and elastomer. Inside stand tiny micropyramids. When pressure is placed on the sensor, the micropyramids compress slightly, connecting with an electrode, which sends a signal about the pressure level.

The elastomer material makes the sensor inherently stretchy, but the researchers increased the stiffness at the bottom of each micropyramid, so even when the sensor is stretched and deformed, the micropyramids stay intact. In fact, even when the material is stretched up to 50 percent—the level

of stretching generally needed on a [human body](#)—the sensor retained its high level of sensitivity. The sensor also proved to be robust, not losing any of its sensing capabilities after being stretched 500 times.

Provided by University of Chicago

### **Incorporating sensors into robotics**

The applications for a stretchable pressure sensor are wide-ranging, but Wang points to the recent COVID-19 pandemic as proof for their immediate need. Many people stuck at home were relegated to talking with their doctors through virtual telemedicine and couldn't get the diagnostic or therapeutic care that they needed.

In the future, a robot could provide such a service. Wang and his team tested their sensor on a soft robotic hand, which was able to use the pressure sensor to grasp a human wrist and record a pulse waveform. Such a robot could also use the pressure sensor to provide physical therapy to patients by putting controlled massage pressure onto body parts.

The sensor could also act as an electronic skin on a prosthesis. For example, a soft robotic prosthetic hand could ultimately sense the pressure its fingers feel when picking up an object.

Wang and his team are working to add multiple sensors to the robot [hand](#)—expanding them to multiple fingers and adding new sorts of [sensors](#) that can feel texture—and are beginning collaborations to design future prosthetic applications.

Other authors include Qiang Zou, Yang Li, Yuzhen Chen, Shan-Yuan Teng, Jane T. Kelleher, Romain Nith, Ping Cheng, Nan Li, Wei Liu, Shilei Dai, Youdi Liu, Alex Mazursky, Jie Xu, Lihua Jin, Pedro Lopes.

**More information:** Qi Su et al, A stretchable and strain-unperturbed pressure sensor for motion interference-free tactile monitoring on skins, *Science Advances* (2021). [DOI: 10.1126/sciadv.abi4563](#)

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