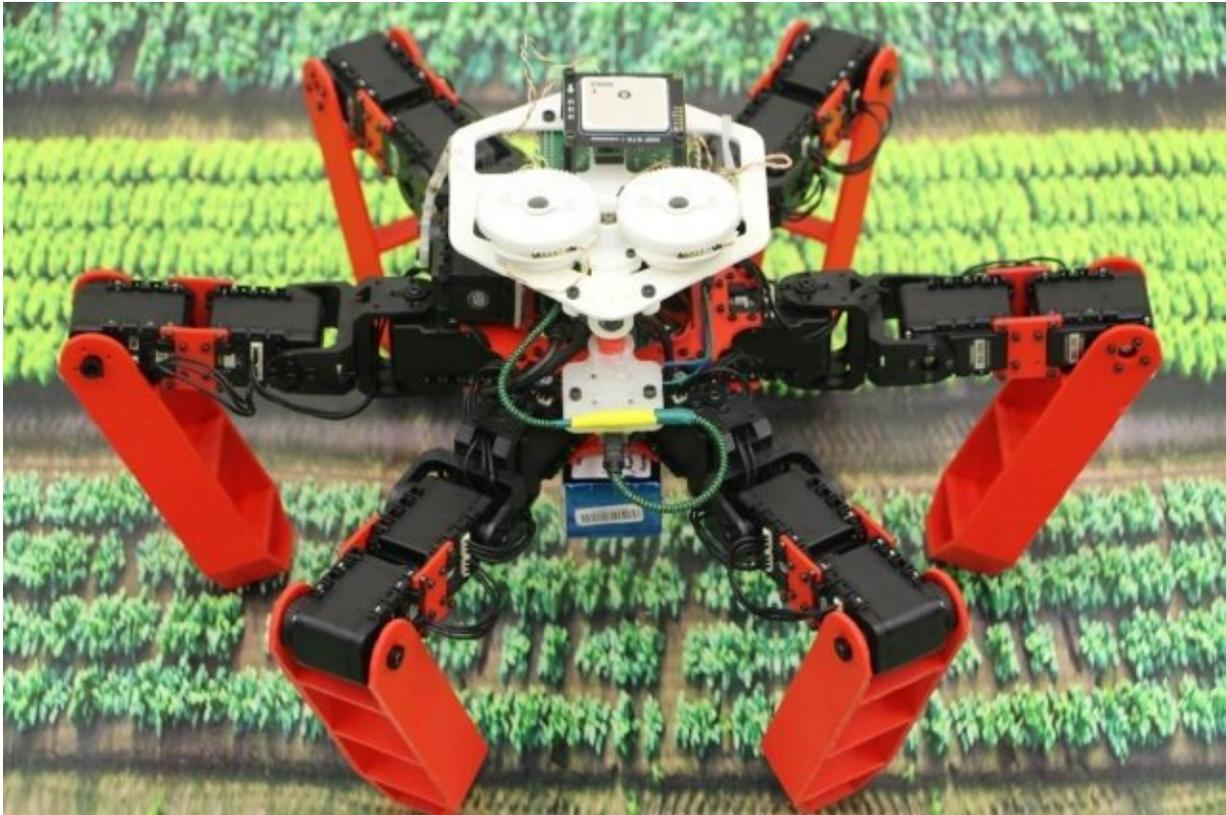


Insect-inspired AI for autonomous robots

June 15 2022



A walking robot that uses sky polarization for navigation. Credit: Julien Dupeyroux

Small autonomous mobile robots, such as drones, rovers, and legged robots, promise to perform a wide range of tasks, from autonomously monitoring crops in greenhouses to last-kilometer delivery. These applications require robots to operate for extended periods while

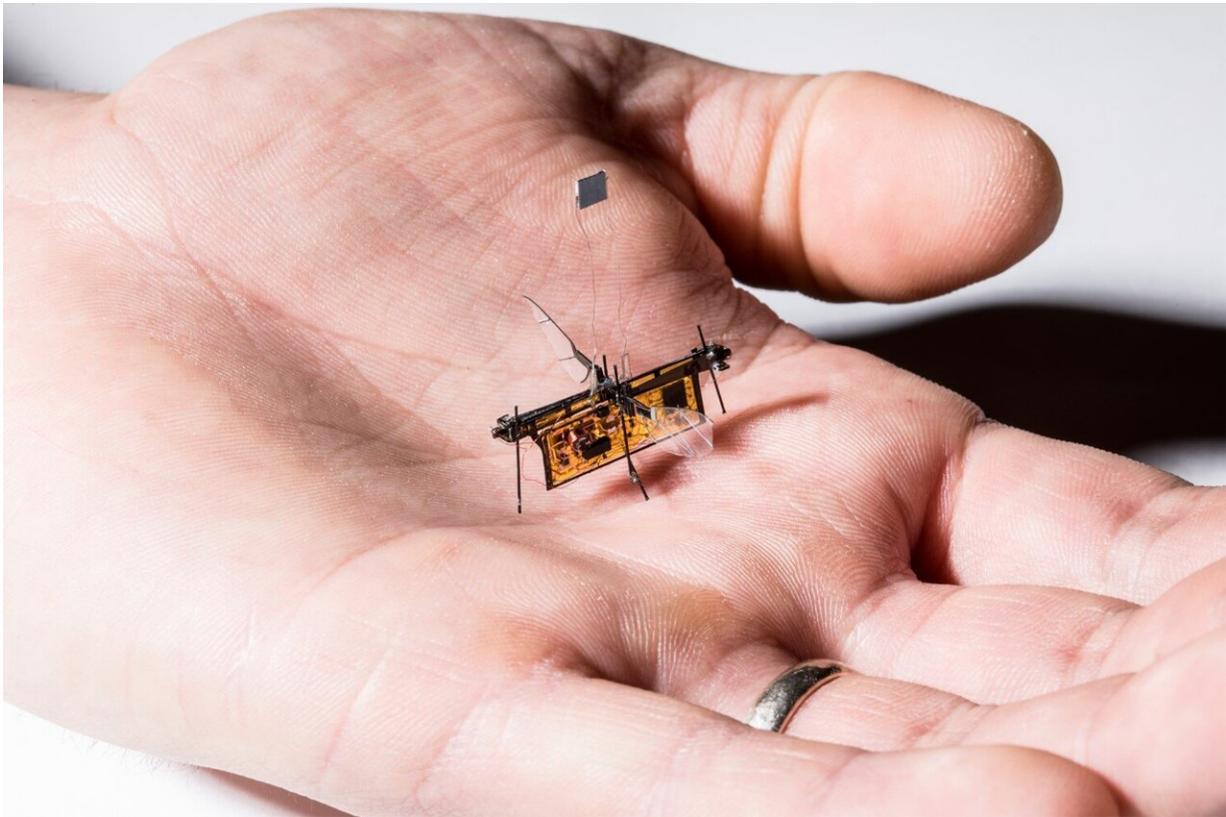
performing complex tasks, often in unknown, changing, and complicated environments.

In a review article published in *Science Robotics* on June 15, researchers from Delft University of Technology, the University of Washington and the University of Sheffield argue that one should draw inspiration from [insects](#) when creating the AI for small, autonomous robots. Insect intelligence is characterized by its minimalistic yet robust solutions. They use these to behave successfully in complex, dynamic environments.

In the article, the researchers explain governing principles that underlie the efficiency and robustness of insect intelligence. They also give an overview of existing robotics research that has leveraged these principles and identify challenges and opportunities ahead. In particular, advances in biology and technology allow for more fine-grained investigations of insect brains. Moreover, progress in sensing and computing hardware will enable robots to approach the [energy efficiency](#) and speed of insect sensing and neural processing. These developments will accelerate the creation of insect-inspired AI for [autonomous robots](#), leading to start-ups in this field.



Swarm of tiny drones is able to localize gas leaks. Credit: Guido de Croon



The first wireless flying robotic insect takes off. Credit: Sawyer Fuller

More information: G. C. H. E. de Croon, Insect-inspired AI for autonomous robots, *Science Robotics* (2022). [DOI: 10.1126/scirobotics.abl6334](https://doi.org/10.1126/scirobotics.abl6334).
www.science.org/doi/10.1126/scirobotics.abl6334

Provided by Delft University of Technology

Citation: Insect-inspired AI for autonomous robots (2022, June 15) retrieved 19 September 2024

from <https://techxplore.com/news/2022-06-insect-inspired-ai-autonomous-robots.html>

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